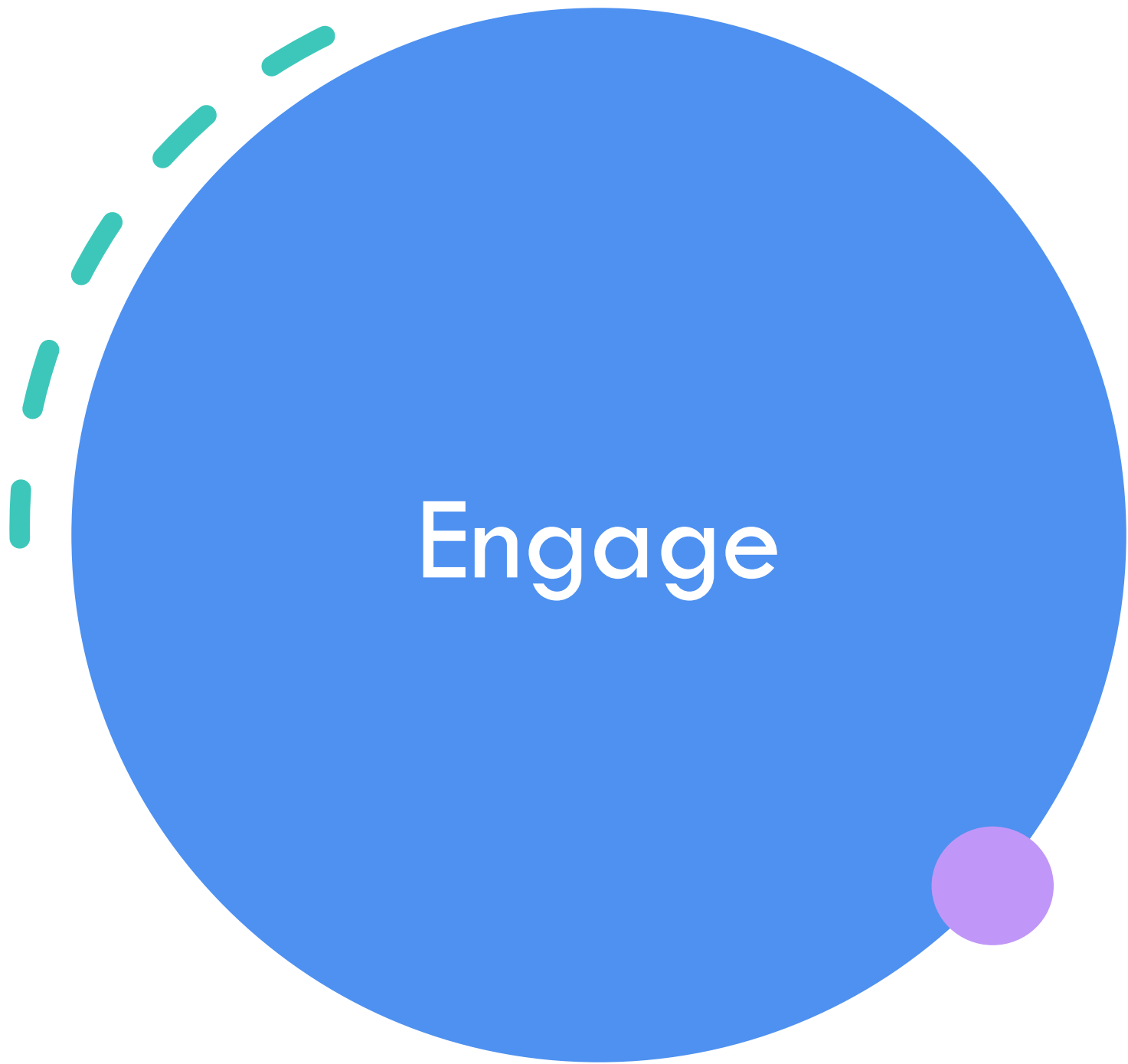


Lesson 1

# Robot Basics: Meet Your Robot



NextWaveSTEM



Engage



Hi, Rapid  
Responders!



**Today's Big Idea:** Robots can be controlled by humans or by programs.

We will learn:

- **The parts of a robot**
- **How to safely drive a robot**
- **That robots can follow instructions called a program**

# Mission Briefing

Welcome recruits!

You have been selected to join the Rapid Response League.

Before you can deploy your robot into disaster zones, you must complete robot training.

Your robot must pass the training course by navigating through the practice area safely and accurately.



# Robot Questions



What is a robot?

What jobs do robots do?

How do robots know what to do?

# Meet Your Robot

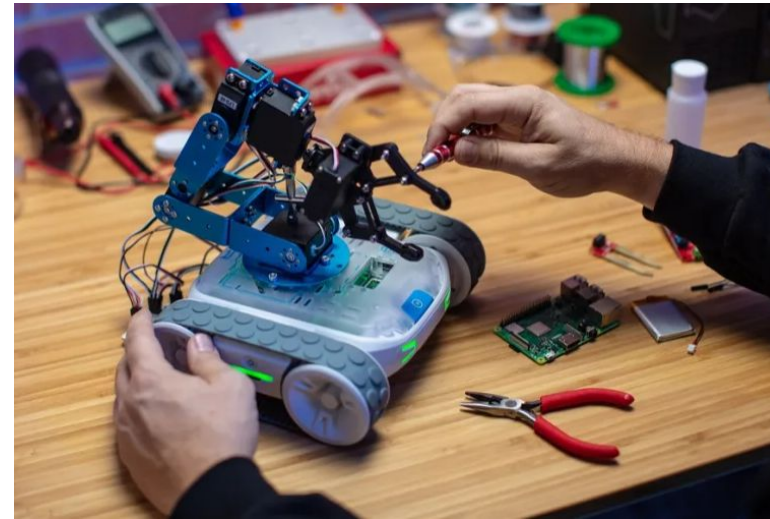
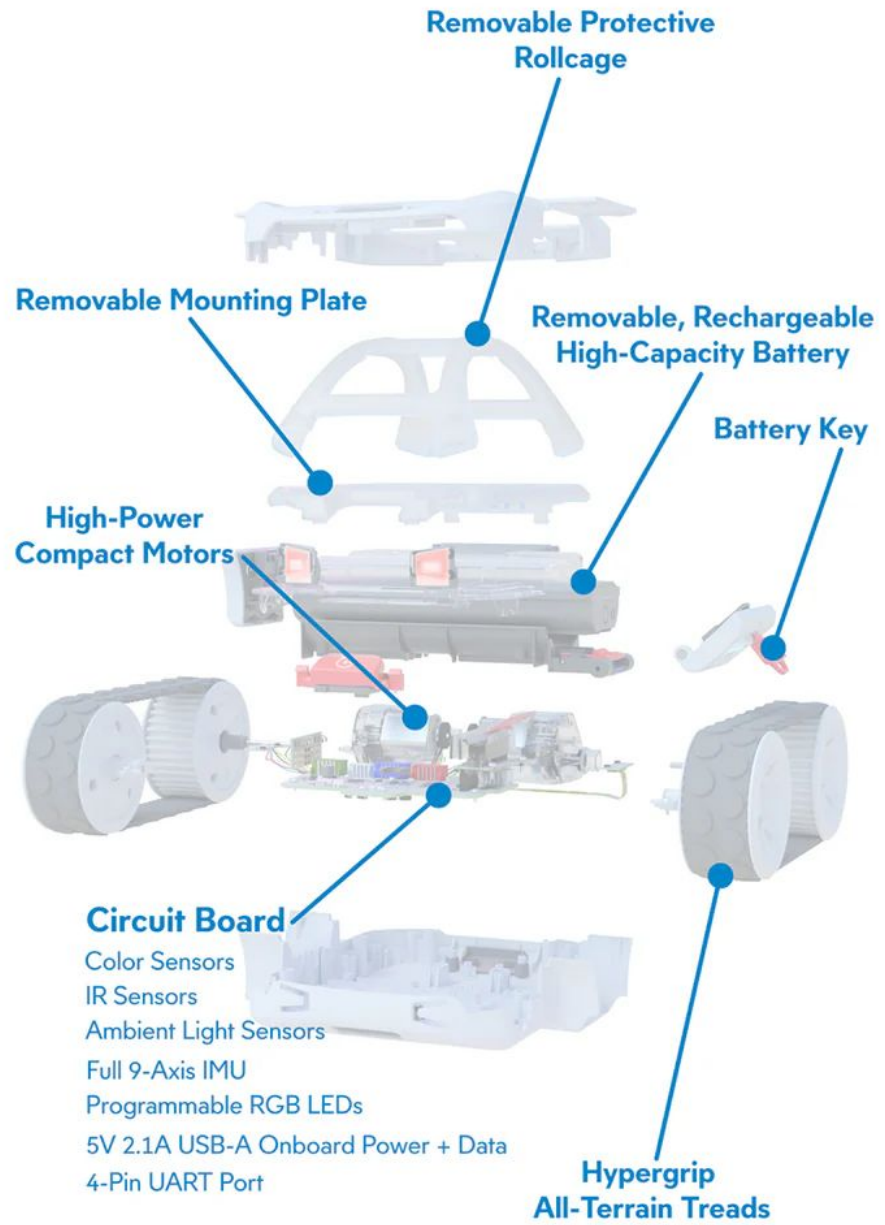
Take a look at your  
**Sphero RVR+**

Can you identify:

- Power button
- Wheels
- Battery compartment
- Sensors
- Lights



# Meet Your Robot



# Robot Safety Rules



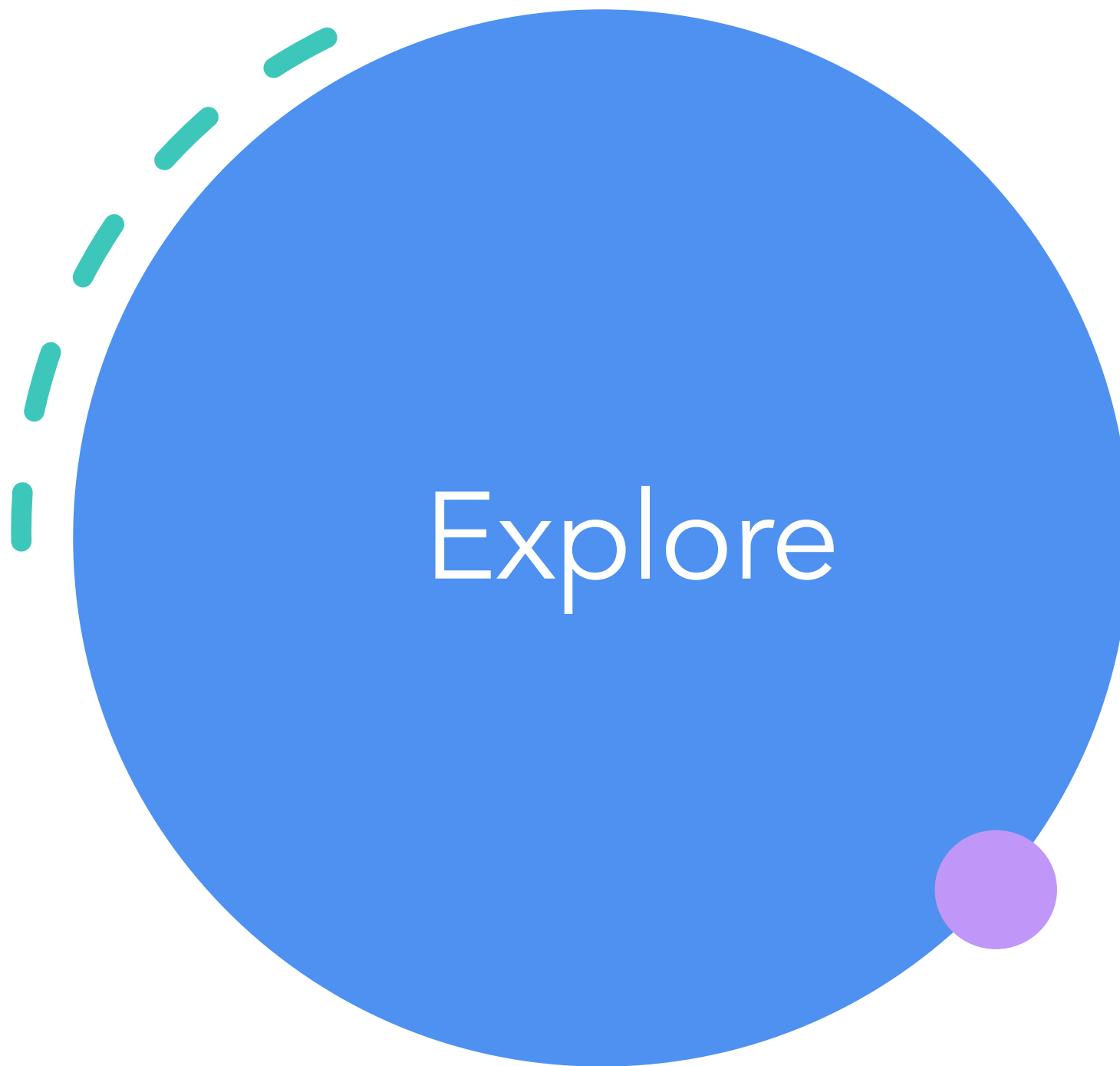
Keep robots on the floor

Keep fingers away from wheels

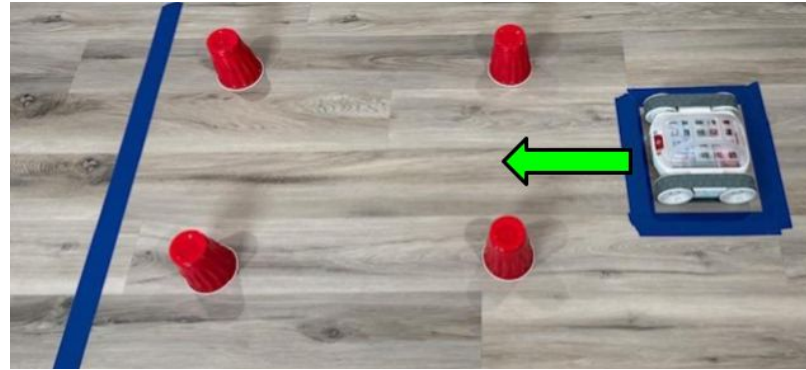
Stop robot if it is out of control

Carry robots carefully

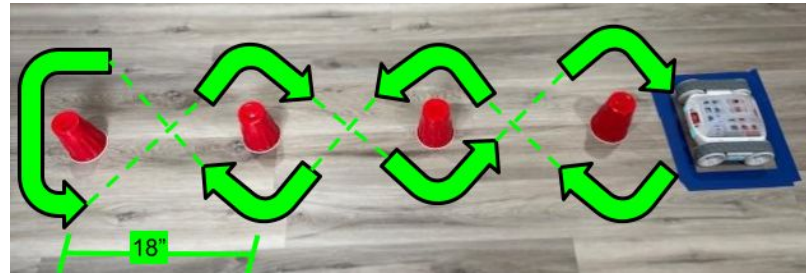
Only run programs when area is clear



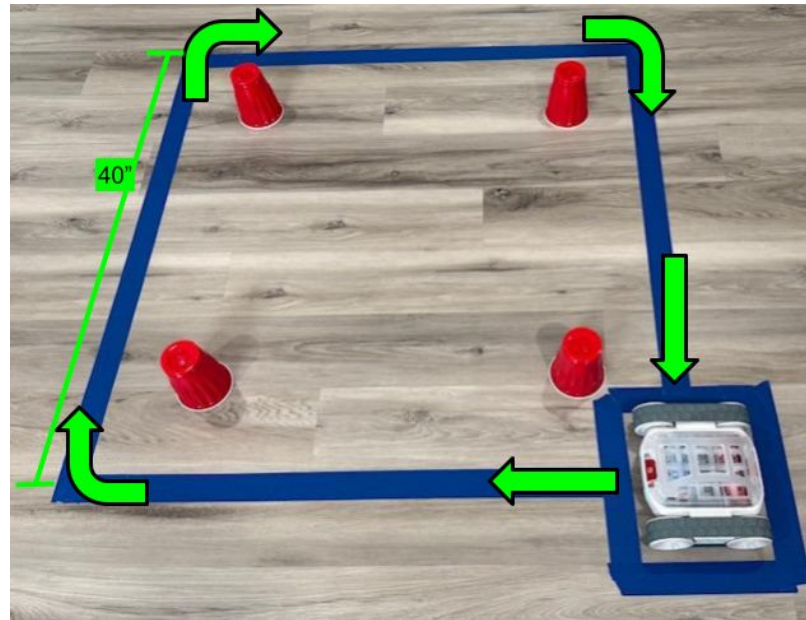
# Training Courses



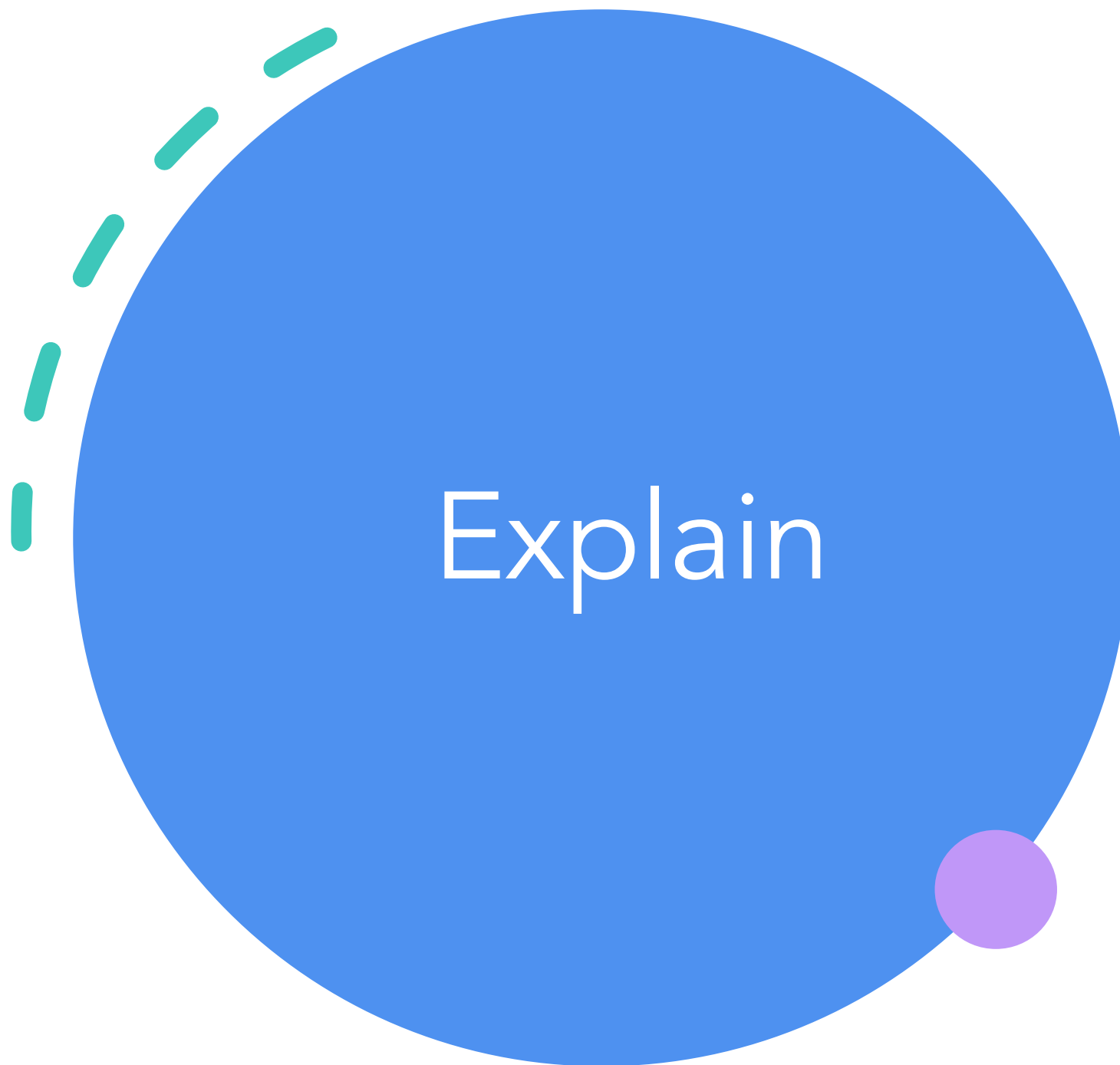
Stop on a Dime



Slalom



Perfect Square



# Manual Driving

Was it easy to drive perfectly?

Did the robot always do exactly what you wanted?

Would it be easier if the robot could drive itself?

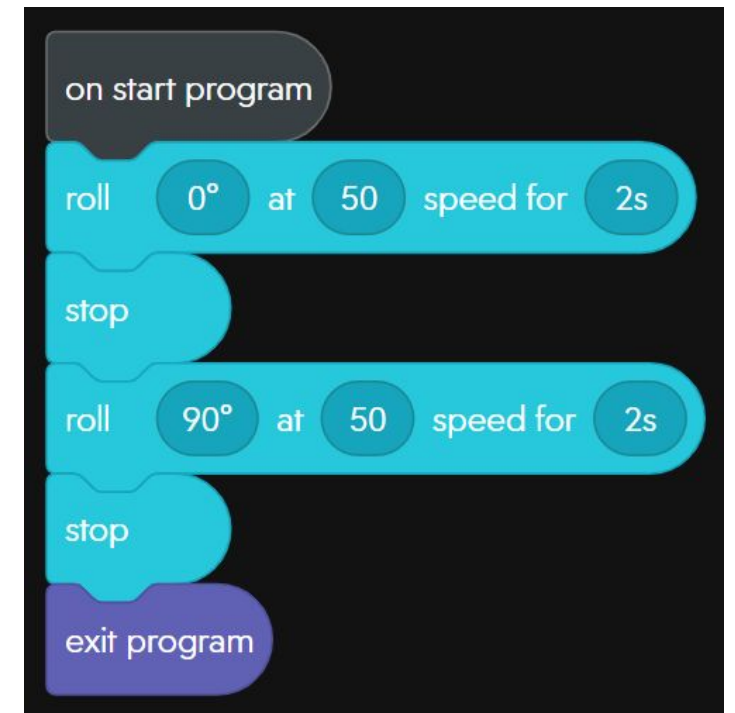
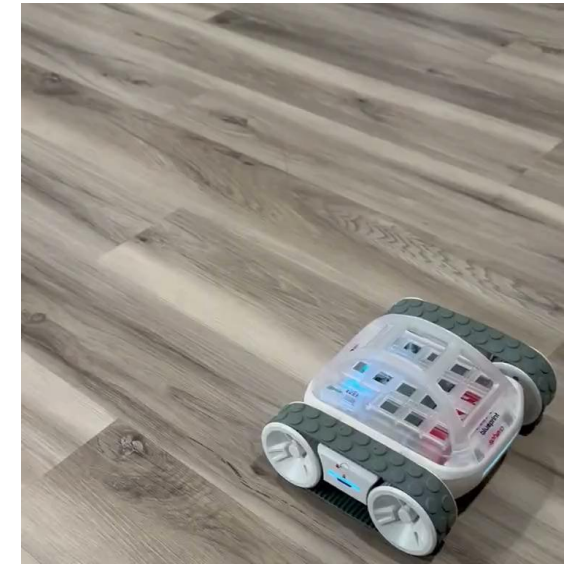


# Program

A **program** is a set of instructions that tells a robot what to do.

Example:

- Drive forward
- Stop
- Turn right
- Drive forward
- Stop



# Uploading a Program to RVR

Create a new program

Choose settings for new program: name, blocks, and RVR

Pull blocks from the left into your program screen

Continue until your program is complete

Click start to upload to RVR

+ CREATE PROGRAM

**Create a New Program**

Program Name

Choose Program Type  
 DRAW  BLOCKS  TEXT

Choose Compatible Robots  
 SPHERO BOLT+  SPHERO BOLT  
 SPHERO RVR/RVR+  SPHERO MINI

CANCEL CREATE

**Movements**

- roll 0° at 0 speed for 0s
- roll 0° at 0 max speed for 0cm
- drive on
- spin 0° for 0s
- speed 0
- stop
- heading 0°
- raw motor left 0 right 0 for 0s
- reset aim

on start program  
 roll 0° at 50 speed for 2s

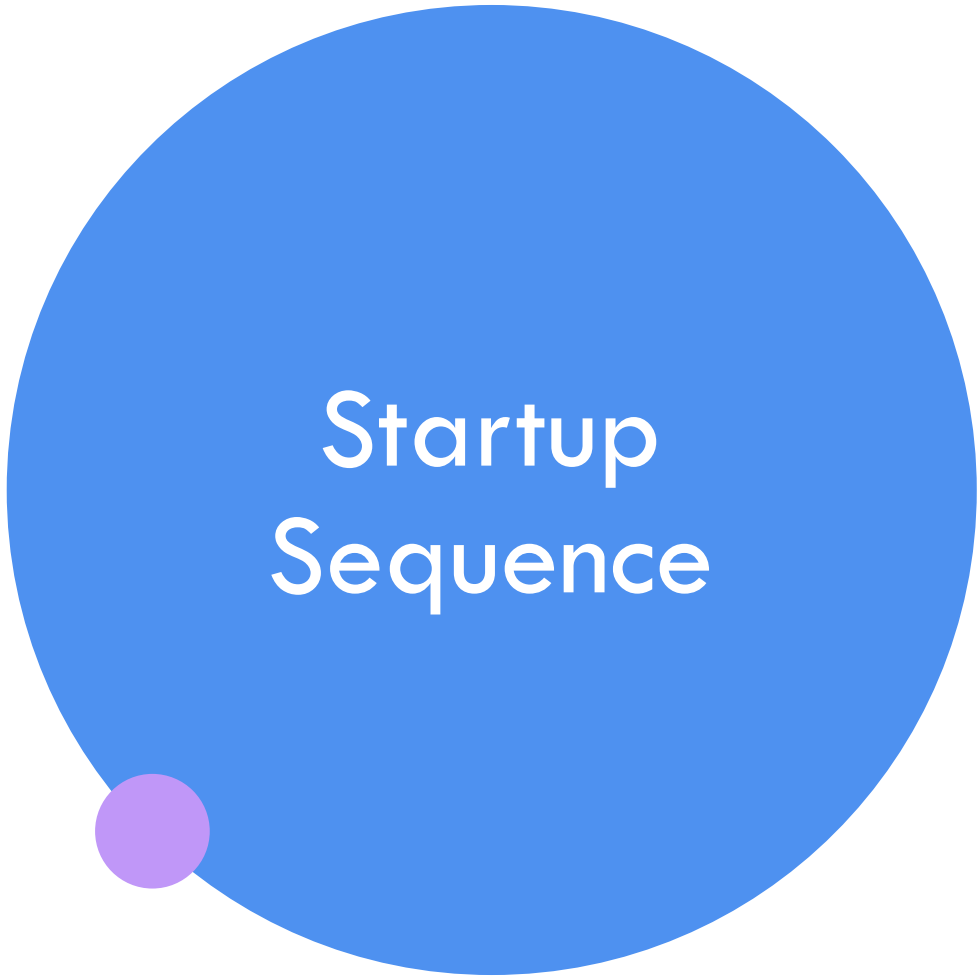
on start program

- roll 0° at 50 speed for 2s
- stop
- roll 90° at 50 speed for 2s
- stop
- exit program

▶ START



Elaborate



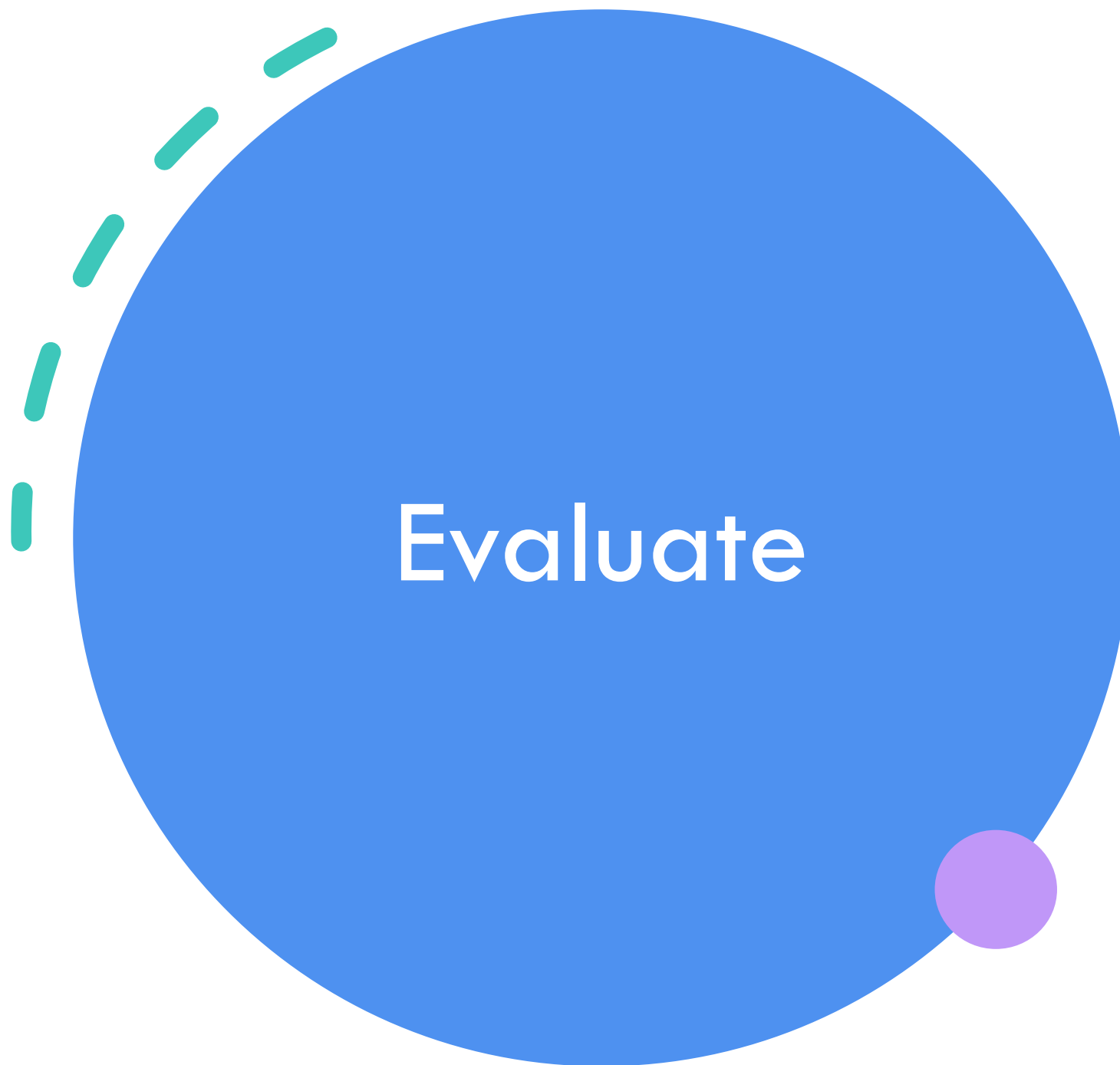
## Startup Sequence



### Rules & Requirements

- ❑ Turn lights on
- ❑ Drive forward
- ❑ Make a sound
- ❑ Flash lights
- ❑ End program

Done with your startup sequence? Add more to your program! You could make the robot dance on startup, or add a few turns!



# Exit Ticket

Now's your chance to show what you learned!  
Answer the following questions on your  
Activity Sheet.

1. What is a robot?
2. What is a program?
3. Did your program work perfectly the first time? If not, what happened?

Great Work,  
Rapid  
Responders!





# Credits & Attributions

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Slides are designed using Canva Elements.